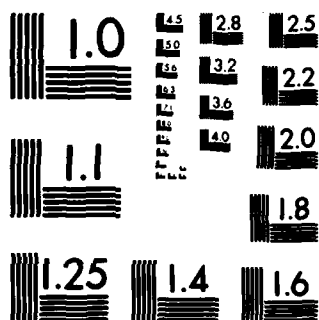


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CONFIDENCE INTERVALS USING THE REGENERATIVE
METHOD FOR SIMULATION OUTPUT ANALYSIS

by

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TECHNICAL REPORT NO. 3

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1. INTRODUCTION

The regenerative method is a mathematically rigorous procedure for obtaining confidence intervals for steady state parameters. In order to properly assess the regenerative method, it is necessary to discuss those characteristics that make a confidence interval "good."

2. QUALITATIVE STRUCTURE OF CONFIDENCE INTERVALS

Given a parameter μ , a confidence interval for μ is generally based on a limit theorem of the form

$$(2.1) \quad (r_t - \mu)/v_t \Rightarrow L$$

as $t \rightarrow \infty$, where L is a finite r.v. with a continuous distribution function; the parameter t measures the simulation effort required to obtain r_t and v_t . The processes r_t and v_t will be called a point estimate (for μ) and a normalizing process, respectively; we shall always assume v_t is positive. To obtain an approximate 100 $(1 - \alpha)\%$ confidence interval for μ , select z_1, z_2 such that $P(z_1 \leq L \leq z_2) = 1 - \alpha$. Then, for large t ,

$$(2.2) \quad [r_t - z_2 v_t, r_t - z_1 v_t]$$

contains μ with probability $1 - \alpha$. The following hierarchy of properties largely determines the quality of the confidence interval.

- a.) consistency of r_t : if r_t is not consistent, v_t does not tend to zero, and confidence interval half-length does not shrink to zero with increasing t .
- b.) asymptotic mean square error of r_t : in general, r_t is asymptotically normal. Then, there exists a non-negative σ such that

$$(2.3) \quad t^{1/2}(\tau_t - \mu) \Rightarrow \sigma N(0,1) .$$

Squaring and taking expectations through (2.3), we observe that

$MSE(\tau_t) \sim \sigma^2/t$. Consequently, one wants to choose τ_t so that σ^2 is as small as possible.

- c.) expected half-width of confidence interval: by (2.2), the expected half-width of the confidence interval is $(z_2 - z_1)Ev_t$. In general, when asymptotic normality holds, $(z_2 - z_1)Ev_t \sim (z_2 - z_1)v/t^{1/2}$ for some v ; the goal is to minimize v .
- d.) variability of half-width of confidence interval: the variance of the half-width is given by $(z_2 - z_1)^2 \text{var } v_t$. Under quite general conditions, $(z_2 - z_1)^2 \text{var } v_t \sim (z_2 - z_1)^2 \alpha/t$; the goal is to minimize α .
- e.) approximation error: Let $\Delta_t = |P(z_1 \leq (\tau_t - \mu)/v_t \leq z_2) - P(z_1 \leq L \leq z_2)|$ be the coverage error for the confidence interval. Berry-Esseen considerations suggest that, in general, $\Delta_t \sim \beta/t^{1/2}$; minimization of β is desirable.

3. THE REGENERATIVE METHOD

Loosely speaking, a regenerative process is one which looks like a sequence of independent and identically distributed (i.i.d.) r.v.'s, when viewed on an appropriate random time scale. More precisely, $X = \{X(t) : t \geq 0\}$ is a regenerative process with regeneration times $0 = T_0 < T_1 < \dots$ if $\{\tau_k, X(s) : T_{k-1} \leq s < T_k\}$ is a sequence of i.i.d. random elements, where $\tau_k = T_k - T_{k-1}$. For examples of such processes, see

Crane and Lemoine (1977). Given a real-valued function defined on the state space of X ,

$$(3.1) \quad r_t = \frac{1}{t} \int_0^t f(X(s)) ds \rightarrow r \text{ a.s.}$$

under mild assumptions on X and f . The goal of a steady state simulation is to produce confidence intervals for r .

If

$$N(t) = \max \{k \geq 0 : T_k \leq t\}$$

and

$$y_1 = \int_{T_{1-1}}^{T_1} f(x(s)) ds ,$$

then

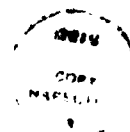
$$(3.2) \quad r_t \approx \bar{y}_{N(t)} / \bar{t}_{N(t)}$$

where $\bar{Y}_n, \bar{\tau}_n$ are the sample means of the Y_1 's and τ_1 's, respectively. Regenerative structure ensures that $\{(Y_1, \tau_1) : 1 \leq 1\}$ is a sequence of i.i.d. random vectors, so that (3.1) and (3.2) together suggest that $r = EY_1/E\tau_1$. Then, by (3.2),

$$r_L - r \approx \bar{z}_{N(t)} / \bar{r}_{N(t)}$$

where $Z_k = Y_k - r \tau_k$ has mean zero. Standard central limit theory arguments prove that

$$t^{1/2}(r_\varepsilon - r) \Rightarrow \mathcal{ON}(0,1)$$

[illegible]

where $\sigma^2 \triangleq \sigma^2(Z_1)/E\tau_1 < \infty$, if $E(Y_1^2 + \tau_1^2) < \infty$. Furthermore,
 $\eta_c \rightarrow \sigma$ a.s., where $\eta_c^2 = s_{N(c)}^2 / \bar{\tau}_{N(c)}$ and

$$s_n^2 = \frac{1}{n-1} \sum_{i=1}^n (Y_i - (\bar{Y}_n / \bar{\tau}_n) \tau_i)^2.$$

We conclude that

$$(r_c - r) / v_c \Rightarrow N(0,1)$$

where $v_c = |\eta_c| / c^{1/2}$ is the normalizing process for the regenerative method. The qualitative structure of the regenerative confidence interval can be summarized as follows:

- a.) r_c is consistent for r ,
- b.) $MSE(r_c) \sim (\sigma^2(Z_1)/E\tau_1)/c$ (note that any confidence interval method using the sample mean r_c as a point estimate will have the same MSE),
- c.) $(z_2 - z_1)Ev_c \sim 2z(\alpha)\sigma(Z_1)/(E\tau_1 \cdot c)^{1/2}$, where $z(\alpha)$ solves $P\{N(0,1) \leq z(\alpha)\} = 1 - \alpha/2$,
- d.) $c(z_2 - z_1)^2 \text{var } v_c \rightarrow 0$ (in fact, $(z_2 - z_1)^2 \text{var } v_c \sim \alpha^2/c^2$, see GLYNN and IGLEHART (1984)),
- e.) β is currently unknown.

Note that β is a reflection of approximation error due to the bias of r_c and skewness/kurtosis effects. It is to be anticipated that the i.i.d.

structure associated with the regenerative viewpoint can be used to reduce these errors. For example, MEKETON and HEIDELBERGER (1982) developed a point estimate which is asymptotically equivalent to r_c , but which significantly reduces bias. Also, GLYNN (1982) proposed a procedure for reducing θ in the closely related problem of estimating r on the time scale of regenerative cycles.

As discussed above, the regenerative method is a theoretically sound procedure for the steady state confidence interval problem. The main advantages of the method are:

- i.) its good asymptotic properties (for example, $\sigma^2(v_c) = O(1/t^2)$ indicates the accurate "variance constant estimation" possible with the regenerative method),
- ii.) the ability to make small-sample corrections to reduce approximation error,
- iii.) the i.i.d. structure allows one to develop procedures for a host of other estimation problems (e.g. comparison of stochastic systems; see HEIDELBERGER and IGLEHART (1979)),
- iv.) no prior parameters are needed as input for the method, other than run length.

The main disadvantages of the method are:

- i.) the requirement to identify regeneration times means that the method is hard to "black box",
- ii.) the method may behave unsatisfactorily if the expected time between regenerations is long. (Estimation of parameters for such simulations is likely to be difficult using any method.)

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
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